

Grant Number: 104526

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Project title: COSMOS: CO-existence Simulation Modeling of radars for Self-driving

The following files have been archived:

COSMOS_Data Repository Report_UoB_V2	Data repository report describing the the measurement scenarios, and data structure of various sensors used for data collection campaign conducted by the University of Birmingham (UoB) and the project partners from 15/09/21 – 19/09/21 at Horiba MIRA test track.
COSMOS_UoB_RepositoryA	Dataset containing radar, lidar, video and GPS data for the use cases 1b, 2g, and 2d from the archived repository overview document